

TRANSITIVE & CONJUGATION

Consider $V_4 \subset A_4$ Consider

$$\alpha: V_4 \times A_4 \rightarrow A_4 : (\sigma, \tau) \mapsto \sigma \tau \sigma^{-1}$$

$$\text{Recall: } (12)(34)(ijk)(34)(12) = (\quad)$$

$$\text{2\& then } = (i)(zj)$$

$$\text{then } (12)(34)(1jz)(34)(12) = (i)(zjkj)$$

So α sends $\{(ijk)\} \subseteq A_4$ to itself

$$\text{i.e. } \text{Orb}((123)) \subseteq \{(ijk)\}$$

$$\text{Orb}((123)) \neq A_4$$

There must be multiple orbits.

Def: $\alpha: G \times X \rightarrow X$ is called transitive if

$$\text{Orb}(x) = X.$$

Def: $\alpha: G \times X \rightarrow X : (g, x) \mapsto gxg^{-1}$ is called action by conjugation

We will apply this action to subgroups:

Def: Two subgroups of G , H & K are called conjugate if $\exists g \in G$ s.t. $gH = Kg$ ($gHg^{-1} = K$)

Conjugacy is an equivalence relation:

equivalence classes are called conjugacy classes

$$\text{Eg } \left\{ \begin{pmatrix} a & b \\ c & d \end{pmatrix} \mid a, b, c, d \in \mathbb{Z}, \det = \pm 1 \right\}$$

$$\text{Complex Roots: } \begin{pmatrix} 1 & 1 \\ 0 & -1 \end{pmatrix}, \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 1 \\ 1 & -1 \end{pmatrix}$$

$$\text{Rational Roots: } \begin{pmatrix} 1 & m \\ 0 & 1 \end{pmatrix} \quad m \geq 0,$$

$$\begin{pmatrix} -1 & -m \\ 0 & -1 \end{pmatrix} \quad m \geq 0, \quad \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}, \text{ \& } \begin{pmatrix} 1 & 1 \\ 0 & -1 \end{pmatrix}$$

Irrational Roots: Infinitely many!

Related to approximation of quadratic
irrationals

$$\text{In particular: } R = \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix} \quad L = \begin{pmatrix} 1 & 0 \\ 1 & 1 \end{pmatrix}$$

$$\text{Each } \pm R^{\alpha_1} L^{\alpha_2} R^{\alpha_3} L^{\alpha_4} \dots R^{\alpha_{2n-1}} L^{\alpha_{2n}}$$

will have a distinct class for distinct sequences
(α_i).

Notation: If H and K are conjugate in G , i.e.
 $\exists g$ s.t. $gHg^{-1} = K$ we write $H^g = K$ &
 $H = K^{g^{-1}}$

HW Let $H, K < G$ & $H^g = K$.

Prove $H \cong K$

Recall that $N \triangleleft K$ iff $gNg^{-1} = N \quad \forall g \in G$.
i.e. $N^g = N \quad \forall g \in G$

Remark: On cycle structure:

Theorem: Let σ & $\tau \in S_n$, same $n \geq 2$.
Then σ & $\tau\sigma\tau^{-1}$ have the same cycle structure.

Proof: $\forall i \in \{1, \dots, n\}$, consider $\sigma(i) = j$, same $1 \leq j \leq n$.
Then $(\tau\sigma\tau^{-1})(\tau(i)) = \tau\sigma(i) = \tau(j)$

So $\sigma: i \mapsto j$
 $\tau\sigma\tau^{-1}: \tau(i) \mapsto \tau(j) \quad \square$

Corollary: $V_4 \triangleleft A_4$

Proof: All elts of V_4 (excl. e) are $(ij)(kl)$, so
 $g \vee g^{-1} \in V_4 \quad \forall g \in A_4$ & $v \in V_4$ So $V_4 \triangleleft A_4 \quad \square$

SYLOW'S THEOREMS

We are going to talk about subgp structure some more.

We have discussed $V_4 \triangleleft A_4 \triangleleft S_4$ — some examples

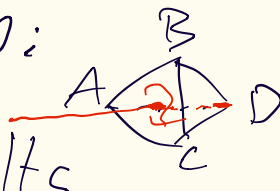
We have Lagrange's theorem — gives necessary conditions for a subgp to exist in finite gps.

If $H < G$ then $|G| = |H| \cdot k$, $k \in \mathbb{N}$

But this says nothing about existence.

[Eg] Consider A_4 , orientation preserving rotations of a tetrahedron (12 elts).

Rotations of each face form a subgp:
 $\langle (ABC) \rangle = \{e, (ABC), (ACB)\}$ — 3 elts



Rotations by π of an edge eg. $\begin{matrix} A & B \\ \diagdown & / \\ C & D \end{matrix} \mapsto \begin{matrix} C & B \\ \diagdown & / \\ D & A \end{matrix}$

$\langle (AD)(BC) \rangle = \{e, (AD)(BC)\}$ — 2 elts

All such rotations together form a subgp.

$V_4 = \{e, (AD)(BC), (AC)(BD), (AB)(CD)\}$ — 4 elts

And that's it! No subgp of order 6.

Is there a simple statement that determines existence of subgps? Unfortunately not, but there is a theory guaranteeing the existence of some subgps.

Defn Let p be prime and let G be a group s.t. every $g \in G$ has order a power of p . We call G a p -group.

[Here we skip all discussion of Normalisers, centralisers, class eqn]

Theorem (Sylow's First Theorem)

Let G be a finite group and let α be the largest power of the prime p in the order of G , i.e. $|G| = p^\alpha s$, $(p, s) = 1$. Then for each $0 \leq \beta \leq \alpha$, $\exists$ a subgp of G of order p^β .

Defn Such subgps of max. order p^α are called Sylow p -subgps of G .

Remark: Recall $\text{ord}(g) \mid |G| \quad \forall g \in G$

So $|G| = p^\alpha$ means $\text{ord}(g)$ is a prime power.

HW Prove or find a counterexample to:
 $|G| = p^\alpha$ if and only if every elt of G has prime power.

Theorem (Sylow's Second & Third Theorems)

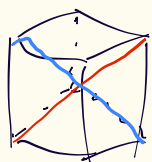
Let $|G| = p^\alpha s$, $(p, s) = 1$, p prime. Let P be a Sylow p -subgp, i.e. $|P| = p^\alpha$. Then every Sylow p -subgp of G is conjugate to P .
Moreover, if the number of conjugates is n_p then $n_p | s$ & $n_p \equiv 1 \pmod{p}$.

Remark. Conjugation shuffles all Sylow p -subgps around, i.e. Sylow p -subgps form an orbit of the action of conjugation on subgps.

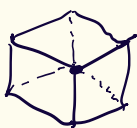
Corollary: Let $|G| = p^\alpha s$, $(p, s) = 1$, & # of conjugate p -Sylow subgps is 1.
Then the p -Sylow subgp. is normal.

Proof: Conjugation permutes subgps. Let N be the p -Sylow subgp. Since there is only one conjugate, $gNg^{-1} = N \quad \forall g \in G$ i.e. $N \triangleleft G$.

Eg Cube rotational symmetries, S_4 , $|S_4| = 4 \cdot 3 \cdot 2 = 3 \cdot 2^3$



Diagonal axis



3 rotations about this axis $\cong \mathbb{Z}_3$
(3-Sylow subgroup)

of 3-Sylow subgps is $n_3 \equiv 1 \pmod{3}$ & $n_3 | 8$

$$n_3 \in \left\{ \underset{1 \pmod{3}}{1}, \underset{2 \pmod{3}}{2}, \underset{1 \pmod{3}}{4}, \underset{2 \pmod{3}}{8} \right\}$$

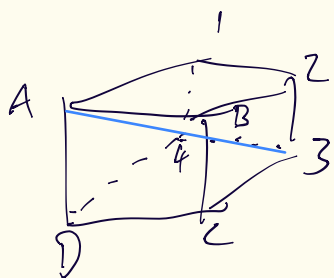
4 pairs of diagonals gives
4 subgps of order 3.

To check: distinct diagonals ^{$n_p = 4$} correspond to distinct subgps of S_4 .

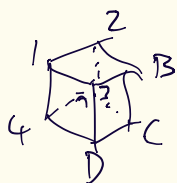
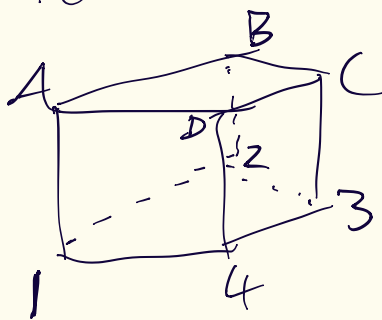
Let $H, K \leq S_4$ be 3-Sylow subgps of distinct diagonals

From Sylow's theorem, $gHg^{-1} = K$, some $g \in G$

Consider a single 120° rotation ccw $\pi \in H$



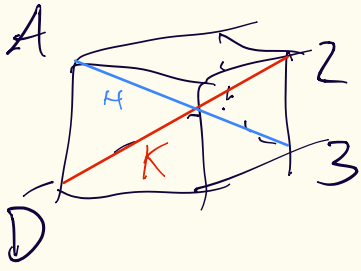
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 π



It is clear no non-trivial rot. through another diag axis will fix A or 3. So gps are distinct.

So $n_3 = 4$.

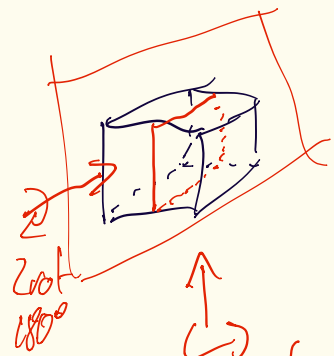
For conjugacy: Let g take the diag. of H to K . Then $gHg^{-1} = K$



g^{-1} takes $D2$ to $A3$, H is some rotation about $A3$, g takes $A3$ to $D2$. So $D2$ is fixed, so $gHg^{-1} \subseteq K$.

Reversing the argument: $g^{-1}Kg \subseteq H$
Hence $gHg^{-1} = K$.

Now for 2-Sylow Subgps, i.e. $|H| = 8$



4 rotations ($R=90^\circ, R^2, R^3, R^4$)

2 rotations, 180°

So 8 rotation subgp fixing this plane. 3 planes, $n_2 = 3 \equiv 1 \pmod{2}$